Arpan Gujarati, Mitra Nasri, Björn B. Brandenburg

Lower-Bounding the MTTF for systems with (m,k) constraints and IID iteration failure probabilities



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Mean Time To Failure Lower-Bounding the MTTF for systems with (m,k) constraints and IID iteration failure probabilities

Independent and Identically Distributed

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= multiple feedback control loops + distributed hosts + shared communication network





+ shared communication network



= multiple feedback control loops + distributed hosts



+ shared communication network



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Safety-critical NCS must be fail-operational

i.e., continue functioning despite EMI-induced failures

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What is a good active replication scheme?

Problem



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What is a good active replication scheme?

- **Opportunity:** controller inherently robust to occasional disturbances

... to provide engineers with an objective metric for comparing different active replication schemes



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(1) Fault Modeling: Transient faults modeled using **Poisson** distribution, empirically-derived peak EMI rates



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Control loop iteration deviates from its failure-free execution

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(2) **Probabilistic Analysis:** Characterize how often a single control loop iteration "fails"

At least *m* iterations, out of any **k** consecutive loop iterations must be correct

(3) Reliability Analysis: Upper-bound the likelihood that the control system "fails beyond recovery"





... to provide engineers with an objective metric for comparing different active replication schemes



(1) Fault Modeling: Transient faults modeled using **Poisson** distribution, empirically-derived peak EMI rates

This probability is upper-bounded by **F**, which satisfies the IID property w.r.t. each iteration (under submission)

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Given F, lower-bound the Mean Time To Failure (MTTF)





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Given F, lower-bound the mean time to <u>failure</u> (MTTF) Outline Failure = Violation of the (m,k) constraint:



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Probability density function (PDF)
f(t) = P(first (m,k) violation at time t)

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Outline

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Given F, lower-bound the mean time to <u>failure</u> (MTTF) Outline

- Discrete probability density function (dPDF) g(n) = P(first (m,k) violation in the nth iteration)
- Probability density function (PDF) f(t) = P(first (m,k) violation at time t)
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- Mean time to failure (MTTF) MTTF = E [system lifetime] = $\int_{0}^{\infty} tf(t) dt$







Given F, lower-bound the mean time to <u>failure</u> (MTTF) Outline •••••••• **Failure = Violation of the** (m,k) constraint: Discrete probability density function (dPDF) g(n) = P(first (m,k) violation in the n^{th} iteration)Probability density function (PDF) f(t) = P(first (m,k) violation at time t) Mean time to failure (MTTF) MTTF = E [system lifetime] = $\int_{0}^{\infty} tf(t) dt$ 3 Evaluation



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1||2||3||4| ••• |n-k-1||n-k||n-k+1||n-k+2| ••• |n-3||n-2||n-1||n|

g(n) = P(first (m,k) violation in the n^{th} iteration)



At least *m* iterations, out of any k consecutive loop iterations must be correct

C1: Less than *m* correct iterations out of last *k* iterations

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C2: (*m*,*k*) constraints not violated any time before the *n*th iteration

g(n) = P(first (m,k) violation in the n^{th} iteration)

$$P(C1) = \binom{k-1}{k-m} F^{(k-m+1)} (1-F)^{m-1}$$

n-k-1||n-k||n-3|4| 1 **12**

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Computationally D((?) challenging

At least *m* iterations, out of any k consecutive loop iterations must be correct

C1: Less than *m* correct iterations out of last *k* iterations

C2: (*m*,*k*) constraints not violated any time before the *n*th iteration

Requires evaluating all possible combinations of failed and successful iterations among the first n - 1 iterations.



a-within-consecutive-b-out-of-c:F system

ding dPDF (2/3) -k+1||n-k+2| === |n-3||n-2||n-1||n|

C2: (*m*,*k*) constraints not violated any time before the *n*th iteration



P(C2) = ? Requires evaluating all possible combinations of failed and successful iterations among the first n – 1 iterations.

modeled as

• consists of c ($c \ge a$) linearly ordered components, • fails iff at least a (a \leq b) components fail among any b consecutive components.


Lower-bounding dPDF (2/3) n-k-1||n-k||n-k+1||n-k+2| === |n-3||n-2||n-1||n

C2: (*m*,*k*) constraints not violated any time before the *n*th iteration

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• consists of c ($c \ge a$) linearly ordered components, fails iff at least a (a \leq b) components fail among any b consecutive components.

$$k - m + 1, \ k, \ n - 1)$$

Lower-bounding dPDF (3/3)

 $P(C1) = \begin{pmatrix} k-1\\ k-m \end{pmatrix}$

 $P(C2) >= R_{abc}(I)$

$$F^{(k-m+1)}(1-F)^{m-1}$$

$$k - m + 1, k, n - 1)$$

 $P(C1) = \begin{pmatrix} k-1 \\ k-m \end{pmatrix}$ $|P(C2)\rangle > = R_{abc}(R)$ $g(n) \ge g_{LB}(n) = \binom{k-1}{k-m} F^{(k-m+1)}$

Lower-bounding dPDF (3/3)

$$F^{(k-m+1)}(1-F)^{m-1}$$

$$k - m + 1, \ k, \ n - 1)$$

$$^{(+1)}(1-F)^{m-1}R_{abc}(k-m+1, k, n-1)$$



Given F, lower-bound the mean time to <u>failure</u> (MTTF) Outline **Failure = Violation of the** (m,k) constraint: Discrete probability density function (dPDF) g(n) = P(first (m,k) violation in the nth iteration) Probability density function (PDF) f(t) = P(first (m,k) violation at time t) Mean time to failure (MTTF) MTTF = E [system lifetime] = $\int_{0}^{\infty} tf(t) dt$ 3 Evaluation



At least *m* iterations, out of any k consecutive loop iterations must be correct



Lower-bounding PDF using dPDF lower bound **f(t)** *GLB*(*n*)



GLB(n)

Lower-bounding PDF using dPDF lower bound **f(t)** $g_{LB}(n)$

 $g_{LB}(n)$ lower-bounds the probability of the first system failure any time during the nth iteration



Lower-bounding PDF using dPDF lower bound **f(t)** $g_{LB}(n)$



Lower-bounding PDF using dPDF lower bound **f(t)** $g_{LB}(n)$



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$$g(n) \ge g_{LB}(n) = \binom{k-1}{k-m} F^{(k-m)}$$
$$\int_{(n-1)T}^{nT} f(t) \ge g_{LB}(n)$$
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$^{(n+1)}(1-F)^{m-1}R_{abc}(k-m+1, k, n-1)$

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#	Case	Definition	Туре
1	a = 0	$R_1(a,b,c) = 0$	Exact
2	a = 1	$R_2(a,b,c) = P_S^c$	Exact
3	$a=2\wedge c\leq 4b$	$R_{3}(a,b,c) = \sum_{i=0}^{\left\lfloor \frac{c+b-1}{b} \right\rfloor} {\binom{c-(i-1)(b-1)}{i}} P_{F}^{i} P_{S}^{c-i}$	Exact
4	$a = 2 \land c > 4b$	$R_4(a, b, c) = R_3(a, b, b + t - 1)(R_3(a, b, b + 3))^u$ where $t = (c - b + 1) \mod 4$ and $u = \lfloor \frac{c - b + 1}{4} \rfloor$	LB
5	$egin{array}{c} a>2\wedge c\leq 2b\wedge \ a=b \end{array}$	$R_5(a,b,c) = egin{cases} 1 & 0 \leq c < a \ 1 - P_F^a - (c-k) P_F^a P_S & a \leq c \leq 2a \end{cases}$	Exact
6	$a>2\wedge c\leq 2b\wedge c$	$R_{6}(a,b,c) = \sum_{i=c-a+1}^{c} {\binom{c}{i}} P_{S}^{i} P_{F}^{c-i}$	Exact
	$a eq b \land c \leq b$		
7	$a>2\wedge c\leq 2b\wedge c$	$R_{7}(a,b,c) = \sum_{i=0}^{a-1} {\binom{b-s}{i}} P_{F}^{i} P_{S}^{b-s-i} M(a',s,2s)$	Exact
	$a \neq b \land c > b$	where $s = c - b$ and $a' = a - i$,	
		1 $a' > s$	
		$R_2(a',s,2s)$ $a'=1$	
		and $M(a', s, 2s) = \begin{cases} R_3(a', s, 2s) & a' = 2 \end{cases}$	
		$R_5(a',s,2s)$ $a'>2\wedge a'=s$	
		$R_7(a', s, 2s)$ $a' > 2 \land a' \neq s$	
8	$a > 2 \land c > 2b$	$R_8(a, b, c) = R_{\phi}(a, b, b + t - 1)(R_{\phi}(a, b, b + 3))^u$	LB
		where $t = (c - b + 1) \mod 4$ and $u = \lfloor \frac{c - b + 1}{4} \rfloor$,	
		$\int R_5(a,b,c) a=b$	
		and $R_{\phi}(a,b,c) = \langle R_6(a,b,c) \mid a \neq b \land a \leq b \rangle$	
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TABLE I. Type indicates whether the reliability definition for that respective case is an exact value or a lower bound.



[12, §11.4.1] (Eqs. 11.9 and 11.10) [12, §11.4.1] (Eq. 11.16)

[12, §9.1.1] (Eqs. 9.2, 9.9, and 9.20) [12, §7.1.1] (Eq. 7.2)

[12, §11.4.1] (Eq. 11.14)

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Problem

Complex definition

 ${}^{1}R_{abc}(k-m+1, k, n-1)$

- Multiple sub-cases
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- Multiple sub-cases
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Symbolic integration not an option!



$$g(n) \ge g_{LB}(n) = \binom{k-1}{k-m} F^{(k-m-1)}(k-m)$$

Computing g_{LB}(n) for a given < m, k, n, F > is easy *m*, *k*, *F* are constants for a given system

$^{(+1)}(1-F)^{m-1}R_{abc}(k-m+1, k, n-1)$



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Computing g_{LB}(n) for a given < m, k, n, F > is easy
► m, k, F are constants for a given system

But what about n?

$^{(+1)}(1-F)^{m-1}R_{abc}(k-m+1, k, n-1)$



$$g(n) \ge g_{LB}(n) = \binom{k-1}{k-m} F^{(k-m+1)} (1-F)^{m-1} R_{abc}(k-m+1, k, n-1)$$

Computing $g_{LB}(n)$ for a given < m, k, n, F > is easy ▶ *m*, *k*, *F* are constants for a given system

But what about *n*?

 \blacktriangleright n varies from 0 to ∞

$$\int_{(n-1)T}^{nT} f(t) \ge g_{LB}(n) \qquad MTTF = \int_0^\infty tf(t) dt$$



*G*LB(*d*₀) *G*LB(*d*₁) *G*LB(*d*₂) ∎ *G*LB(*d*L-1) *G*LB(*d*L)

 $MTTF = \int_0^\infty t \times f(t) \, dt$

{splitting $(0, \infty)$ into a finite number of subintervals $(0, d_0T]$, $(d_0T, d_1T]$, ..., $(d_{D-1}T, d_DT]$, and (d_DT, ∞) ; and dropping the integrals for subintervals $(0, d_0T]$ and (d_DT, ∞) since we are interested in lower-bounding the MTTF}

$$\geq \sum_{i=0}^{D-1} \int_{d_i T}^{d_{i+1}T} t \times f(t) dt$$

{since for all $t \in (d_iT, d_{i+1}T], t \ge d_iT$ }

$$\geq \sum_{i=0}^{D-1} \left(d_i T \times \int_{d_i T}^{d_{i+1}T} f(t) \, dt \right)$$

{splitting each subinterval $(d_iT, d_{i+1}T]$ into multiple subintervals $(d_iT, (d_i + 1)T], ((d_i + 1)T, (d_i + 2)T], \dots, ((d_{i+1}-1)T, (d_{i+1})T]$, each of length T}

$$= \sum_{i=0}^{D-1} \left(d_i T \times \left(\sum_{j=0}^{d_{i+1}-d_i-1} \int_{(d_i+j)T}^{(d_i+j+1)T} f(t) \, dt \right) \right)$$

{since $\int_{(d_i+j)T}^{(d_i+j+1)T} f(t) dt \ge g_{LB}(d_i+j+1)$ (from Eq. 2)}

$$\geq \sum_{i=0}^{D-1} \left(d_i T \times \left(\sum_{j=0}^{d_{i+1}-d_i-1} g_{LB}(d_i+j+1) \right) \right)$$

{since $g_{LB}(n)$ is decreasing with increasing n, for each integer j in the interval $[0, d_{i+1}-d_i-1], g_{LB}(d_i+j+1) \ge g_{LB}(d_i+d_{i+1}-d_i-1+1) = g_{LB}(d_{i+1})$ }

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{simplifying the innermost summation}

$$=\sum_{i=0}^{D-1}\left(d_iT imes g_{LB}(d_{i+1}) imes (d_{i+1}-d_i)
ight)$$

GLB(*d*₀) *GLB*(*d*₂) ∎ *GLB*(*d*_{L-1}) *GLB*(*d*_L)

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$$= \sum_{i=0}^{D-1} \left(d_i T \times \left(\sum_{j=0}^{d_{i+1}-d_i-1} \int_{(d_i+j)T}^{(d_i+j+1)T} f(t) \, dt \right) \right)$$

{since $\int_{(d_i+j)T}^{(d_i+j+1)T} f(t) dt \ge g_{LB}(d_i+j+1)$ (from Eq. 2)}

$$\geq \sum_{i=0}^{D-1} \left(d_i T \times \left(\sum_{j=0}^{d_{i+1}-d_i-1} g_{LB}(d_i+j+1) \right) \right)$$

{since $g_{LB}(n)$ is decreasing with increasing n, for each integer j in the interval $[0, d_{i+1}-d_i-1], g_{LB}(d_i+j+1) \ge g_{LB}(d_i+d_{i+1}-d_i-1+1) = g_{LB}(d_{i+1})$ }

$$\geq \sum_{i=0}^{D-1} \left(d_i T \times \left(\sum_{j=0}^{d_{i+1}-d_i-1} g_{LB}(d_{i+1}) \right) \right)$$

{simplifying the innermost summation}

$$=\sum_{i=0}^{D-1}\left(d_iT imes g_{LB}(d_{i+1}) imes (d_{i+1}-d_i)
ight)$$



GLB(*d*₀) *GLB*(*d*₂) ∎ *GLB*(*d*_{L-1}) *GLB*(*d*_L)

$$MTTF = \int_0^\infty t \times f(t) \, dt$$

{splitting $(0, \infty)$ into a finite number of subintervals $(0, d_0 T)$, $(d_0 T, d_1 T]$, ..., $(d_{D-1}T, d_D T]$, and $(d_D T, \infty)$; and dropping the integrals for subintervals $(0, d_0 T]$ and $(d_D T, \infty)$ since we are interested in lower-bounding the MTTF}

$$\geq \sum_{i=0}^{D-1} \int_{d_i T}^{d_{i+1}T} t \times f(t) dt \qquad \text{Paper}$$

{since for all $t \in (d_iT, d_{i+1}T], t \ge d_iT$ }

$$\geq \sum_{i=0}^{D-1} \left(d_i T \times \int_{d_i T}^{d_{i+1}T} f(t) \, dt \right)$$

{splitting each subinterval $(d_iT, d_{i+1}T]$ into multiple subintervals $(d_iT, (d_i + 1)T], ((d_i + 1)T, (d_i + 2)T], \dots, ((d_{i+1}-1)T, (d_{i+1})T]$, each of length T}

$$= \sum_{i=0}^{D-1} \left(d_i T \times \left(\sum_{j=0}^{d_{i+1}-d_i-1} \int_{(d_i+j)T}^{(d_i+j+1)T} f(t) \, dt \right) \right)$$

{since $\int_{(d_i+j)T}^{(d_i+j+1)T} f(t) dt \ge g_{LB}(d_i+j+1)$ (from Eq. 2)}

$$\geq \sum_{i=0}^{D-1} \left(d_i T \times \left(\sum_{j=0}^{d_{i+1}-d_i-1} g_{LB}(d_i+j+1) \right) \right)$$

{since $g_{LB}(n)$ is decreasing with increasing n, for each integer j in the interval $[0, d_{i+1}-d_i-1], g_{LB}(d_i+j+1) \ge g_{LB}(d_i+d_{i+1}-d_i-1+1) = g_{LB}(d_{i+1})$ }

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{simplifying the innermost summation}

$$=\sum_{i=0}^{D-1}\left(d_iT imes g_{LB}(d_{i+1}) imes (d_{i+1}-d_i)
ight)$$





Choosing points d_0 , d_1 , ..., d_L













Given F, lower-bound the mean time to <u>failure</u> (MTTF) Outline **Failure = Violation of the**

Discrete probability density function (dPDF) g(n) = P(first (m,k) violation in the nth iteration)

Probability density function (PDF) f(t) = P(first (m,k) violation at time t)



Mean time to failure (MTTF) MTTF = E [system lifetime] = $\int_{0}^{\infty} tf(t) dt$

Evaluation

(m,k) constraint:

At least *m* iterations, out of any k consecutive loop iterations must be correct



Approximating MTTF using simulation

Approximating MTTF using simulation

Biased-coin toss experiment

Tails with probability *F*

system iteration is incorrect

Heads with probability 1 - F
system iteration is correct



Approximating MTTF using simulation

Biased-coin toss experiment

Tails with probability *F*

system iteration is incorrect

Heads with probability 1 - F
system iteration is correct



Each trial Repeat coin toss until the (m,k) constraint is violated
Approximating MTTF using simulation

Biased-coin toss experiment

Tails with probability F

system iteration is incorrect

Heads with probability 1 - F
system iteration is correct

MTTF_{sim} = Average tosses per trial x control period

ent

Each trial Repeat coin toss until the (m,k) constraint is violated

Comparing MTTF_{LB} and MTTF_{sim}



(m, k) = (8, 10)



Comparing MTTF_{LB} and MTTF_{sim}

MTTF increases when F decreased from 10⁻² to 10⁻⁴





Comparing MTTF_{LB} and MTTF_{sim}

MTTF increases when F decreased from 10⁻² to 10⁻⁴ MTTF decreases when *m/k* increased from 3/5 to 98/100



(m, k) = (8, 10)



MTTF_{LB} is always less than MTTF_{sim} 10^{14} 10¹³ $F = 10^{-4}$ 10¹² 10^{11} 10^{10} $F = 10^{-3}$ Time (ms) 10^{9} 10^{8} 10^{7} $F = 10^{-2}$ $F = 10^{-2}$ 10^{6} 10^{5} 10^{4} 10^{3} 10^{2}

(m, k) = (3, 5)

(m, k) = (8, 10)





Comparing MTTF_{LB} and MTTF_{sim} In all cases, MTTF_{LB} and MTTF_{sim} are MTTF_{LB} is always less than MTTF_{sim} roughly of the same orders of magnitude 10^{14} $MTTF_{sim}$ $MTTF_{LB}$ 10¹³ $F = 10^{-4}$ **F** = 10⁻⁴ 10^{12} 10^{11} 10^{10} $F = 10^{-3}$ $F = 10^{-4}$ Time (ms) $F = 10^{-3}$ 10^{9} 10^{8} $F = 10^{-3}$ 10^{7} $F = 10^{-2}$ $F = 10^{-2}$ 10^{6} 10^{5} **F** = 10⁻² 10^{4} 10³ 10^{2}

(m, k) = (3, 5)

(*m*, *k*) = (8, 10)



Comparing time to compute MTTF_{LB} and MTTF_{sim}



Comparing time to compute MTTF_{LB} and MTTF_{sim}



Summary



(1) Fault Modeling: Transient faults modeled using **Poisson** distribution, empirically-derived peak EMI rates

Control loop iteration deviates from its failure-free execution

(2) Probabilistic Analysis: Characterize how often a single control loop iteration "fails"

At least *m* iterations, out of any **k** consecutive loop iterations must be correct

(3) Reliability Analysis: Upper-bound the likelihood that the control system "fails beyond recovery"



Summary



(1) Fault Modeling: Transient faults modeled using **Poisson** distribution, empirically-derived peak EMI rates

Given a bound F on the iteration failure probability, also satisfying the IID property

Control loop iteration deviates from its failure-free execution

(2) Probabilistic Analysis: Characterize how often a single control loop iteration "fails"

At least *m* iterations, out of any **k** consecutive loop iterations must be correct

(3) Reliability Analysis: Upper-bound the likelihood that the control system "fails beyond recovery"

Safe lower bound on the system MTTF for systems with (m, k) constraints







Thank you. Questions?



